

Recall (~~Setup A M A M E L~~)

$$\eta = \eta_1 d\hat{Y}^1 + \eta_2 d\hat{Y}^2$$

$$= \tilde{\eta}_1 d\hat{X}^1 + \tilde{\eta}_2 d\hat{X}^2$$

$$\text{Def. } dy = \left(\frac{\partial \eta_2 \circ \psi}{\partial x^1} - \frac{\partial \eta_1 \circ \psi}{\partial x^2} \right) d\hat{Y}^1 \wedge d\hat{Y}^2 \quad \text{---} \star$$

$$\text{also } = ? \left(\frac{\partial \tilde{\eta}_2 \circ \chi}{\partial x^1} - \frac{\partial \tilde{\eta}_1 \circ \chi}{\partial x^2} \right) d\hat{X}^1 \wedge d\hat{X}^2 ?$$

We showed

$$\textcircled{1} \quad d\hat{X}^j = \sum_{i=1}^2 \frac{\partial X^{-1} \circ \psi}{\partial x^i}^j d\hat{Y}^i$$

$$\begin{aligned} \textcircled{2} \quad \frac{\partial \eta_2 \circ \psi}{\partial x^1} &= \sum_{l,m} \frac{\partial \tilde{\eta}_m \circ \chi}{\partial x^l} \frac{\partial (X^{-1} \circ \psi)^l}{\partial x^1} \frac{\partial (X^{-1} \circ \psi)^m}{\partial x^2} \\ &\quad + \sum_m \tilde{\eta}_m \circ \psi \frac{\partial^2 (X^{-1} \circ \psi)^m}{\partial x^1 \partial x^2} \end{aligned}$$

& $2 \leftrightarrow 1$

Sub into RHS of \star . Second term vanishes because symmetric in $1 \leftrightarrow 2$.

Learning

$$\begin{aligned}
 & \sum_{l,m} \frac{\partial \tilde{\eta}_m \circ \chi}{\partial x^l} \frac{\partial (\chi^{-1} \circ \psi)^l}{\partial x^1} \frac{\partial (\chi^{-1} \circ \psi)^m}{\partial x^2} d\hat{\psi}'_1 d\hat{\psi}'_2 \\
 & + \sum_{l,m} \cancel{\frac{\partial \tilde{\eta}_m \circ \chi}{\partial x^l}} \frac{\partial (\chi^{-1} \circ \psi)^l}{\partial x^2} \frac{\partial (\chi^{-1} \circ \psi)^m}{\partial x^1} d\hat{\psi}'_2 d\hat{\psi}'_1 \\
 & = \cancel{\sum_{l,m} \left(\frac{\partial \tilde{\eta}_m \circ \chi}{\partial x^l} \frac{\partial \tilde{\eta}_l \circ \chi}{\partial x^m} \right) d\hat{\psi}'_1 d\hat{\psi}'_2} \xrightarrow{\text{Swapped}} \\
 & = \sum_{l,m} \frac{\partial \tilde{\eta}_m \circ \chi}{\partial x^l} d\hat{\psi}'_l d\hat{\psi}'^m \\
 & = \cancel{\left(\frac{\partial \tilde{\eta}_2 \circ \chi}{\partial x^1} - \frac{\partial \tilde{\eta}_1 \circ \chi}{\partial x^2} \right)} d\hat{\psi}'_1 d\hat{\psi}'^2 \\
 & \quad (\underline{d\mu \wedge d\mu = 0 \text{ - ex.}})
 \end{aligned}$$

Propⁿ 6.22

① If $\psi: U \rightarrow \Sigma'$ is a parametrization &
 η a 1-form then

$$d\eta(s) = \sum \left(\frac{\partial \eta_2 \circ \psi}{\partial x^1} (\psi^{-1}(s)) - \frac{\partial \eta_1 \circ \psi}{\partial x^2} (\psi^{-1}(s)) \right) d\hat{\psi}'_1(s) d\hat{\psi}'_2(s)$$

is well-defined &

② If $f: \Sigma' \rightarrow \mathbb{R}$ then

$$d(f \wedge \eta) = df \wedge \eta + f \wedge d\eta$$

Proof ① ✓ ② Ex //

Propⁿ 6.23 (Weak Green's Thⁿ)

If η is a 1-form on $\Sigma \subseteq \mathbb{R}^3$ ^{oriented} _{an/surface}

$$\int_{\Sigma} d\eta = 0$$

Proof Choose a partition of unity ρ_α for a cover by parametrizations γ_α .

~~$\gamma_1 \cup \gamma_2 \cup \gamma_3 \cup \gamma_4 \cup \gamma_5$~~

$$\eta = \sum \rho_\alpha \eta$$

$$\therefore d\eta = \sum \rho_\alpha d(\eta)$$

$$\int_{\Sigma} d\eta = \sum_{\alpha} \int_{\gamma_\alpha(U_\alpha)} d(\rho_\alpha \eta)$$

$$\text{supp}(\rho_\alpha \eta) \subseteq \gamma_\alpha(U_\alpha)$$

$$\therefore \text{supp}(d(\rho_\alpha \eta)) \subseteq \gamma_\alpha(U_\alpha)$$

$$\therefore \int_{\Sigma} d\eta = \sum_{\alpha} \int_{\gamma_\alpha(U_\alpha)} d(\rho_\alpha \eta)$$

So it is enough to show $\int_{\gamma_\alpha(M_\alpha)} d(\rho \alpha y) = 0$.

or if $U \subseteq \mathbb{R}^2$ open bounded &
 η a 1-form with $\text{supp } \eta \subseteq U$ then

$$\int_U dy = 0$$

But $\eta = \eta_1 dx^1 + \eta_2 dx^2$

Green's Thm \rightarrow

$$\int_U dy = \int_{\partial U} \left(\frac{\partial \eta_2}{\partial x^1} - \frac{\partial \eta_1}{\partial x^2} \right) dx^1 dx^2$$



$$= \int_{\partial U} \eta_1 dx^1 + \eta_2 dx^2$$

$$= 0 //$$

Prop 7.1

Lemma & WORK

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$$\frac{d}{dt} (R_{\#t} v \delta_{\#t}) = d n_{\#}$$

Proof

We can work locally \Rightarrow to prove equality.

Assume $\psi(x^1, x^2)$ local coordinate parameters as Σ' but suppress their dependence. Then $d\psi =$

$$n = \left\langle \frac{\partial n}{\partial t} \times \frac{\partial n}{\partial x^1}, n \right\rangle d\hat{\psi}^1 + \left\langle \frac{\partial n}{\partial t} \times \frac{\partial n}{\partial x^2}, n \right\rangle d\hat{\psi}^2$$

$$dn = \left(\left\langle \frac{\partial^2 n}{\partial x^1 \partial t} \times \frac{\partial n}{\partial x^1}, n \right\rangle + \left\langle \frac{\partial n}{\partial t} \times \frac{\partial^2 n}{\partial x^1 \partial x^2}, n \right\rangle \right) \xrightarrow{\text{symmetric}} + \left\langle \frac{\partial n}{\partial t} \times \frac{\partial n}{\partial x^2}, \frac{\partial n}{\partial x^1} \right\rangle \xrightarrow{\text{all } \perp n} = 0$$

$$- (\xrightarrow{1 \leftrightarrow 2} d\hat{\psi}^1 \wedge d\hat{\psi}^2)$$

$$= \left(\left\langle \frac{\partial^2 n}{\partial x^1 \partial t} \times \frac{\partial n}{\partial x^2}, n \right\rangle - \left\langle \frac{\partial^2 n}{\partial x^2 \partial t} \times \frac{\partial n}{\partial x^1}, n \right\rangle \right) \xrightarrow{\text{symmetric}} d\hat{\psi}^1 \wedge d\hat{\psi}^2$$

§ 7 GAUSS-BONNET THEOREM

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Note from earlier work that

$$\begin{aligned} Rv_d(x, y) &= \langle \pi(x) \times \pi(y), n \rangle \\ &= \langle n'(x) \times n'(y), n \rangle \end{aligned}$$

so we can calculate it entirely using the Gauss map.

Imagine now we deform Σ' in \mathbb{R}^3 . We want to see how $\int_{\Sigma} Rv_d$ changes.

If we can instead hold Σ' fixed and just assume $n = n_t$ is varying.

~~assumption~~ $\therefore n: [0, 1] \times \Sigma' \rightarrow S^2$

We define a 1-form η on Σ' as

$$\eta(x) = \left\langle \frac{\partial n}{\partial t} \times dn(x), n \right\rangle$$

$$= \cancel{\frac{\partial}{\partial t} (Rv)} \\ = \cancel{\frac{\partial}{\partial t}} \left(\left\langle \frac{\partial n}{\partial x^1} \times \frac{\partial n}{\partial x^2}, n \right\rangle \right) = \cancel{\frac{\partial}{\partial t}} (Rv d\Omega)$$

Lemma 7.2

$\int R v d\Omega_{\Sigma}$ is constant w.r.t area
deform Σ .

Proof

$$\cancel{\frac{d}{dt}} \int R v d\Omega_{\Sigma} = \int d\Omega = 0.$$

Def 7.3 If $\tilde{\Sigma}$ is obtained from Σ by removing two disks and adding a cylinder we call it attaching a handle

