

## Lecture 24

Recall  $\det(V^*)$  is all

multilinear, antisymmetric maps

$$\omega : \underbrace{V \times \dots \times V}_{n = \dim V} \rightarrow \mathbb{R}$$

~~we just proved~~

~~If  $\omega \in$~~

if  $v^1, \dots, v^n$  basis of  $V$  then define

$$[v^1, \dots, v^n](w^1, \dots, w^n) = \det(X^i_j)$$

where  $w^i = \sum_{j=1}^n X^i_j v^j$

Then if  $\omega \in \det(V^*)$

$$\omega = \omega(v^1, \dots, v^n) [v^1, \dots, v^n]$$

$\therefore \det(V^*)$  is 1-dim<sup>l</sup>

Example of proof  $\dim V = 2$ ,  $v^1, v^2$  basis

$$w^1, w^2 \in V$$

$$w^i = X^i_1 v^1 + X^i_2 v^2$$

$$\omega(w^1, w^2) = \omega(X^1_1 v^1 + X^1_2 v^2, X^2_1 v^1 + X^2_2 v^2)$$

$$\begin{aligned}
&= \cancel{x_1^1} x_1^2 \omega(v_1^1, v_1^2) + x_1^1 x_2^2 \omega(v_1^1, v_2^2) \\
&\quad + x_2^1 x_1^2 \omega(v_2^1, v_1^1) + x_2^1 x_2^2 \omega(v_2^1, v_2^2) \\
&\qquad\qquad\qquad \parallel \qquad\qquad\qquad = 0 \\
&\qquad\qquad\qquad - \omega(v_1^1, v_2^2)
\end{aligned}$$

$$= \omega(v_1^1, v_2^2) (x_1^1 x_2^2 - x_2^1 x_1^2)$$

$$= \omega(v_1^1, v_2^2) \det(X)$$

$$= \omega(v_1^1, v_2^2) [v_1^1, v_2^2] (\omega^1, \omega^2)$$

Corollary 6.6

If  $w^1, \dots, w^n, v^1, \dots, v^n$  are two bases

&  $w^i = \sum_j x_j^i v^j$  then

$$[\omega^1, \dots, \omega^n] = \det(x_j^i) [\omega^1, \dots, \omega^n]$$

Proof

$$(\omega = \omega(w^1, \dots, w^n) [w^1, \dots, w^n])$$

~~$$[\omega^1, \dots, \omega^n] = \omega(w^1, \dots, w^n) [w^1, \dots, w^n]$$~~

$$\begin{aligned}
\cancel{[\omega^1, \dots, \omega^n]} &= [v^1, \dots, v^n] (\omega^1, \dots, \omega^n) [w^1, \dots, w^n] \\
&= \det(x_j^i) [w^1, \dots, w^n]
\end{aligned}$$

If  $S \subseteq \mathbb{R}^N$  is a  $n$ -dim<sup>l</sup> submanifold then

we say it is oriented if we have

chosen continuously one half of

$\det(T_x S^*) - \{0\}$ . Call an  $n$ -form

on this half positive.

If  $\psi: U \rightarrow S$  is a parametrization

call it oriented if  $[\frac{\partial \psi}{\partial x^1}, \dots, \frac{\partial \psi}{\partial x^n}]$

is positive.

Prop<sup>n</sup> 6.7

Let  $\chi: V \rightarrow \mathcal{S}$ ,  $\psi: U \rightarrow \mathcal{S}$  be oriented parametrizations with  $\chi(V) = \psi(U)$  and

let  $\rho = \psi^{-1} \circ \chi: V \rightarrow U$ . Then

$$\det J(\rho) > 0.$$

Proof

$$\chi = \psi \circ \rho$$

$$\frac{\partial \chi}{\partial x^i}(x) = \sum_j \frac{\partial \psi}{\partial x^j}(\rho(x)) \frac{\partial \rho^j}{\partial x^i}(x)$$

$$= \sum_j \frac{\partial \rho^j}{\partial x^i}(x) \frac{\partial \psi}{\partial x^j}(\rho(x))$$

$$\parallel J(\rho)_i$$

So from Corollary 6.6

$$\left[ \frac{\partial \psi}{\partial x_1}(p(a)) \dots \frac{\partial \psi}{\partial x_n}(p(a)) \right]$$

$$= \det J(p) \left[ \frac{\partial x}{\partial x_1} \dots \frac{\partial x}{\partial x_n} \right]$$

+ve multiples of each other  $\therefore \det J(p) > 0$

A  $n$ -form  $\omega$  on  $S$  is a choice of  $n$  form at each  $s \in S$ . If  $\psi: U \rightarrow S$  we have

$$\omega = \omega \left( \frac{\partial x}{\partial x_1}, \dots, \frac{\partial x}{\partial x_n} \right) \left[ \frac{\partial \psi}{\partial x_1}, \dots, \frac{\partial \psi}{\partial x_n} \right]$$

$$\omega_{\psi} \quad \omega_{\psi}: U \rightarrow \mathbb{R}$$

Call  $\omega$  smooth if we can cover  $S$  by parametrizations so that each  $\omega_{\psi}$  is smooth.

From ~~Prop 6.8~~ 6. we have

Prop<sup>n</sup> 6.8  $\chi, \psi$  as above then

$$\omega_{\chi} = \det J(p) \circ \omega_{\psi} \circ p$$

Proof

~~$$\omega_{\chi} =$$~~

We have

~~w(x)~~

$$w(x(x)) = w_X(x) \left[ \frac{\partial x}{\partial x_1}(x), \dots, \frac{\partial x}{\partial x_n}(x) \right]$$
$$= w_X(x) \det J(p|x)^{-1} \left[ \frac{\partial \psi}{\partial x_1}(p(x)), \dots, \frac{\partial \psi}{\partial x_n}(p(x)) \right]$$

$$\& w_{(x|x)} = w_{\psi(p(x))} =$$

$$= w_{\psi}(p(x)) \left[ \frac{\partial \psi}{\partial x_1}(p(x)), \dots, \frac{\partial \psi}{\partial x_n}(p(x)) \right]$$

$$\therefore w_X|x| = \cancel{w_X} \det J(p|x) w_{\psi}(p(x)) //$$

This shows that being a smooth  
n-manifold doesn't depend on the choice  
of parametrization as  $w_X$  is smooth  
 $\Leftrightarrow w_{\psi}$  is smooth.

If  $w$  is

Def<sup>n</sup> 6.9 If  $w$  is a smooth  $n$ -form on  $S$

we define

$$\text{supp}(w) = \{x \mid w(x) \neq 0\}$$

Def<sup>n</sup> 6.10 If  $\psi: U \rightarrow S$  is <sup>oriented</sup> an  $n$ -form with  $\text{supp } w \subseteq U$  then

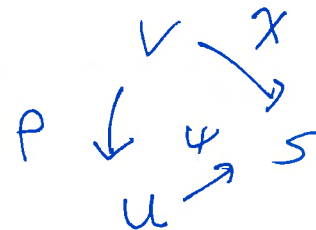
we define

$$I_\psi(w) = \int_U w_\psi \, dx^1 \dots dx^n = \int_U w\left(\frac{\partial \psi}{\partial x^1}(x), \dots, \frac{\partial \psi}{\partial x^n}(x)\right) dx^1 \dots dx^n$$

Prop<sup>n</sup> 6.11 If  $\chi: V \rightarrow S$  <sup>oriented,</sup> with  $\chi(V) = \psi(U)$   
 $\psi: U \rightarrow S$

then

$$I_\chi(w) = I_{\psi \circ \chi} (w)$$



Proof

$$I_{\psi \circ \chi}(w) = \int_U w_{\psi \circ \chi} \, dx^1 \dots dx^n$$

$$= \int_V \det(J(p)) w_{\psi \circ p} \, dx^1 \dots dx^n$$

$$= \int_U w_\psi \, dx^1 \dots dx^n$$

$$= I_\psi(w)$$

NB  $\det J(p) > 0$

as  $\chi, \psi$  both oriented.

$\Rightarrow w_\psi, w_\chi$  +ve multiples of each other

To be sure the integral exists we should insist that  $\text{supp } w$  is compact.  
~~In all our examples where we eat~~  
 What about forms that don't have support in the image of some parameterization? We use a technical trick called a partition of unity.

Def 6.12

If  $S$  is covered by open sets  $U_1, \dots, U_n$  with a partition of unity subordinate to the cover, is a collection of maps

$p_i: S \rightarrow \mathbb{R}$  s.t.

$$\textcircled{1} \quad \sum_i p_i = 1$$

$$\textcircled{2} \quad p_i \geq 0$$

$$\textcircled{3} \quad \text{supp } p_i \subseteq U_i$$

Then the  $p_i \cdot w$  is an  $n$ -form with


$$\text{supp}(p_i w) \subseteq \text{supp}(p_i) \subseteq U_i$$

$$\& \quad w = \sum_i (p_i w)$$

In other words a partition of unity



If  $\varphi_i: U_i \rightarrow S$  is a collection of  
 parametrizations with  $\varphi_i(U_i) = W_i$  then  
 we define

$$\int_S \omega = \sum_i \int_{U_i} I_{\varphi_i}(\omega)$$


Prop<sup>n</sup> 6.17 The integral of an  $n$ -form  
 is well-defined independent of choice  
 of parametrizations and partitions of unity.  
 ↓ End of lecture

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