

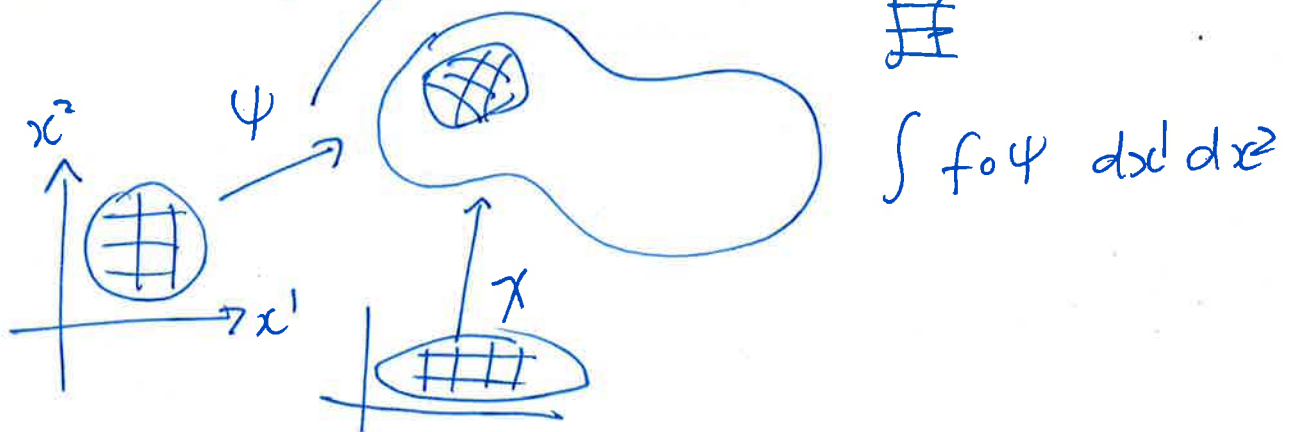
§ 6 Integration

Motivation: Want to integrate $\int_{\Sigma} R dA$

Turns out we need to think of "R dA" as a 2-form and integrate the 2-form.

~~\int forms on a manifold~~
~~* can be integrated over p domain~~
~~submanifold~~

To motivate this think about integrating ~~in~~ ~~of~~ the image of a parametrisation using parameters. Need to integrate in \mathbb{R}^n and see how it changes when we change parametrisation.



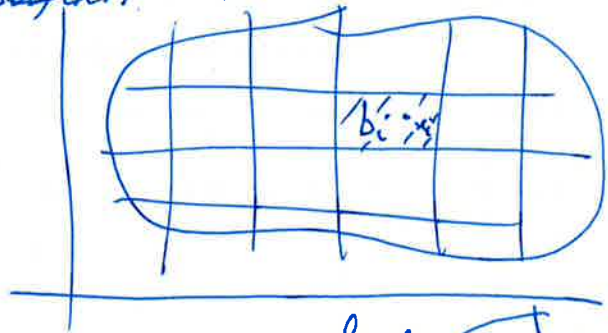
If $R =$ Gauss's cylinder

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Lecture 23 we want $\int_R f(x) dx$. How to do this?

§6 Integration

6.1 Integrals in \mathbb{R}^n



Recall we are particularly interested in $\lim \sum_{i=1}^n f_i(x_i) \text{vol}(b_i)$

Let R be a closed bounded region in \mathbb{R}^n .

& $f: \mathbb{R}^n \rightarrow \mathbb{R}$ cts. ~~Define~~ we define

$\int_R f dx^1 \dots dx^n$. It satisfies:

Propⁿ 6.1

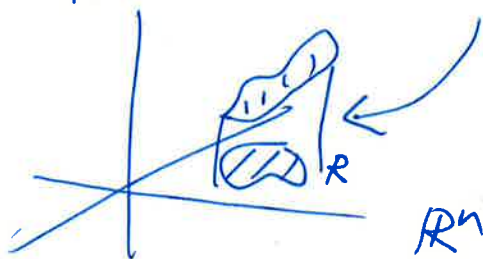
① $f \mapsto \int_R f dx^1 \dots dx^n$ is linear

② If $f(x) \geq 0 \quad \forall x \in R \Rightarrow \int_R f dx^1 \dots dx^n \geq 0$

③ If $f(x) > 0 \quad \int_R f dx^1 \dots dx^n$ is the

volume of

$$\left\{ (x^1, \dots, x^{n+1}) \mid \begin{array}{l} f(x^1, \dots, x^n) \in R \\ 0 \leq x^{n+1} \leq f(x^1, \dots, x^n) \end{array} \right\}$$



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④ If R_1, R_2 are disjoint & $R = R_1 \cup R_2$

$$\int_R f \, dx^1 \dots dx^n = \int_{R_1} f \, dx^1 \dots dx^n + \int_{R_2} f \, dx^1 \dots dx^n$$

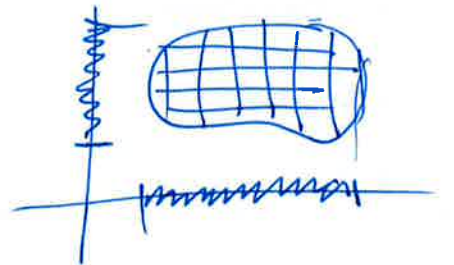
How do we calculate? Do \mathbb{R}^2 case

Thm 6.2 (Fubini) If $R \subseteq \mathbb{R}^2$, closed, bdd
 $f: R \rightarrow \mathbb{R}$ ct

$$\int_R f \, dx^1 \, dy$$

$$= \int \left(\int f(x,y) \, dx \right) dy$$

$$= \int \left(\int f(x,y) \, dy \right) dx$$



Def 6.3 If $U \subseteq \mathbb{R}^n$ open & $f: U \rightarrow \mathbb{R}$
 ct define the support of f

$$\text{supp}(f) = \{ x \mid f(x) \neq 0 \}$$

= smallest closed set
 containing

$$\{ x \mid f(x) \neq 0 \}$$

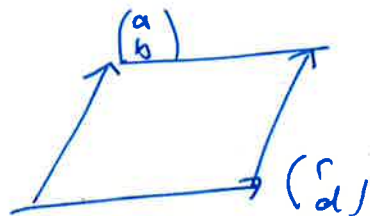
$U \subseteq \mathbb{R}^n$
 U open

If $f: U \rightarrow \mathbb{R}$ & $\text{supp}(f)$ is bounded

then

$$\int_U f \, dx^1 \dots dx^n = \int_{\text{supp}(f)} f \, dx^1 \dots dx^n$$

Recall that \mathcal{A}



is a parallelogram then its area

$$= \left| \det \begin{pmatrix} a & c \\ b & d \end{pmatrix} \right|$$

More generally if $X = (x'_1 \ x'_2 \ \dots \ x'_n)$

$\text{Area}(\text{convex hull } v_1, \dots, v_n \sum t_i v_i \ 0 < t_i \leq 1)$

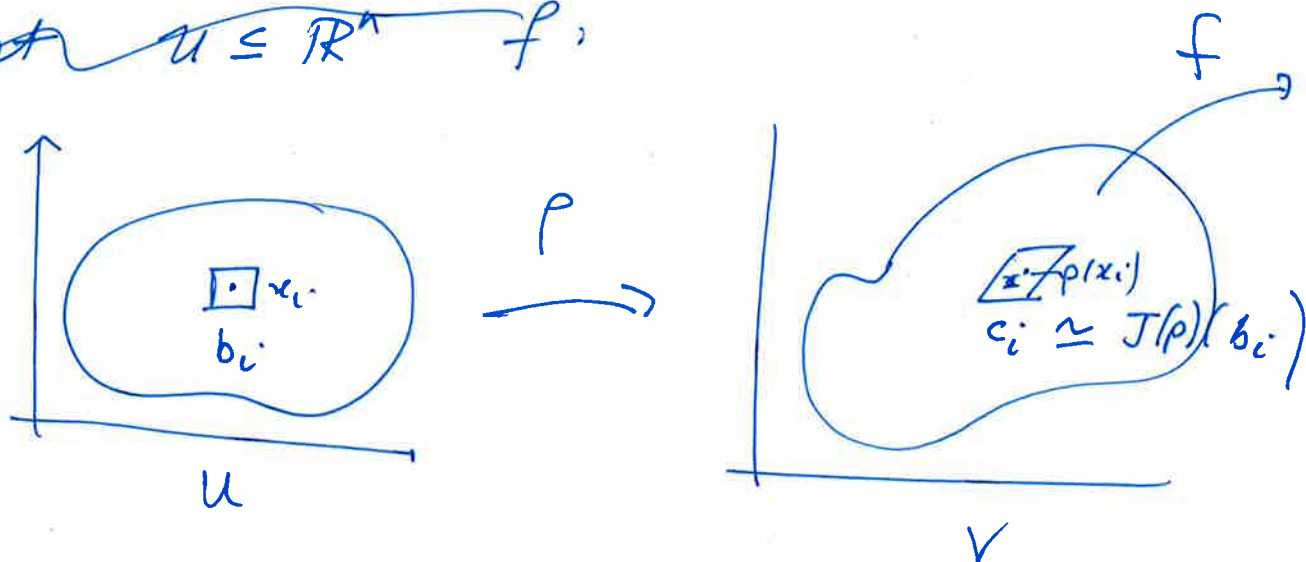
$$= \det X.$$

~~More generally~~

Even more generally if $D \subseteq \mathbb{R}^n$

$$\text{Vol}(X(D)) = |\det X| (\text{Vol } D)$$

Let $u \subseteq \mathbb{R}^n$ f :



$$\int_V f \sim \sum_i f(p(x_i)) \text{Vol}(c_i) \sim \sum_i f(p(x_i)) |\det J(p)| |b_i| \mathbb{R}^n$$

$$\sim \int_u f \circ p |\det J(p)| dx^1 \dots dx^n$$

Th^m 6.4 (Change of variable)

Let $U \subseteq \mathbb{R}^n$ open $f: U \rightarrow \mathbb{R}$ cts

& $\Phi: U \rightarrow V$ a diffeo^m for $V \subseteq \mathbb{R}^n$ open

Let $f: V \rightarrow \mathbb{R}$ have bounded support then

$$\int_V f \, dx^1 \dots dx^n = \int_U f \circ \Phi \, |\det(J(\Phi))| \, dx^1 \dots dx^n$$

where $J(\Phi) = \begin{bmatrix} \frac{\partial \Phi^1}{\partial x^1} & \dots & \frac{\partial \Phi^1}{\partial x^n} \\ \vdots & & \vdots \\ \frac{\partial \Phi^n}{\partial x^1} & \dots & \frac{\partial \Phi^n}{\partial x^n} \end{bmatrix}$

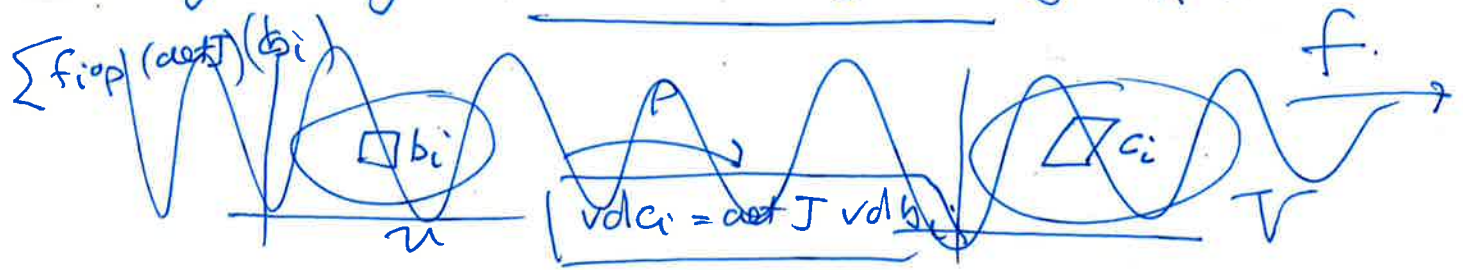
~~Mention how linear transformation changes vol.~~

(Note the absolute value sign here)

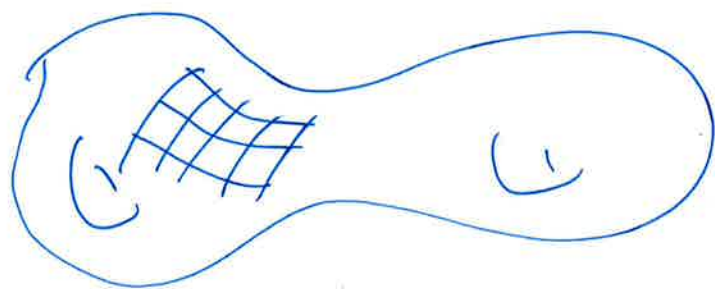
To integrate over submanifolds we need to find a way of integrating which is independent of parameter.

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This amounts to including the $dx^1 \dots dx^n$ into the integrand and integrating volume forms $\sum f_i \, v d(c_i)$



Alternatively you could imagine trying to divide the submanifold into "boxes".



Then what we integrate is something that measures the size of the box like $f(x) dx^1 \dots dx^n \sim f(x_i) v d(b_i)$

we go back to the idea that the size of a box with sides b_1, \dots, b_n in \mathbb{R}^n is

$$|\det(b_1 \ b_2 \ \dots \ b_n)|. \quad \text{Consider } \det(b_1, \dots, b_n)$$

Think of this as a function of n vectors

b_1, \dots, b_n . It has various

properties we capture as follows.

~~On a surface submanifold can~~
 6.2 Volume form and integration

Let V be a vector space of ~~degree~~
 dimⁿ n . An n -form is a ~~linear~~

map $\omega : \underbrace{V \times \dots \times V}_n \rightarrow \mathbb{R}$

which is multilinear & antisymmetric

Multilinear means:

$$\begin{aligned} \omega(v_1, \dots, v_{i-1}, au + bv, v_{i+1}, \dots, v_n) \\ = a \omega(v_1, \dots, v_{i-1}, u, v_{i+1}, \dots, v_n) \\ + b \omega(v_1, \dots, v_{i-1}, v, v_{i+1}, \dots, v_n) \end{aligned}$$

$$\forall v_j, u, v \quad \forall a, b \quad \forall i.$$

antisymmetric means

$$\omega(v_1, \dots, v_i, v_{i+1}, \dots, v_n) = -\omega(v_1, \dots, v_{i+1}, v_i, \dots, v_n)$$

~~linear~~

In particular $\omega(v_1, \dots, v_i, \dots, v_i, \dots, v_n) = 0$.

Examples (1) If $V = \mathbb{R}^n$

$$\omega(v_1, \dots, v_n) = \det(v_i^j) \text{ is}$$

~~anti~~ or n -form.

L... 8

(2) If v^1, \dots, v^n is a basis of V

define $[\omega^1, \dots, \omega^n] (w^1, \dots, w^n)$
 $= \det(X^i_j)$

where $w^i = \sum_j X^i_j v^j$

(3) If $\Sigma \subseteq \mathbb{R}^3$ is an oriented surface with normal n at $s \in \Sigma$ then

$\omega(v, w) = \langle v \times w, n \rangle$

is a 2-form on $T_s \Sigma$

Prop 6.5

Denote by $\det(V^*)$ the vector space (check!) of all n -forms on V .

Prop 6.5 The space of all n -forms is 1-dim. If v^1, \dots, v^n is a basis of V & ω is an n -form then

$\omega = \omega(v^1, \dots, v^n) [v^1, \dots, v^n]$

\uparrow number \uparrow n -form

Proof Let $w^i = \sum_j X_{ij} v_j$

then $\omega(w^1, \dots, w^n) = \omega(\sum_j X_{1j} v_j, \dots, \sum_k X_{nk} v_k)$
 $= \sum_j X_{1j_1} \dots X_{nj_n} \omega(v_{j_1}, \dots, v_{j_n})$

But $w(v_{j_1}, \dots, v_{j_n}) = \begin{cases} 0 & \text{if any two } w(v_1, \dots, v_n) \text{ equal} \\ \text{sgn} \begin{pmatrix} 1 & \dots & n \\ j_1 & \dots & j_n \end{pmatrix} \cdot w(v_1, \dots, v_n) \end{cases}$

Standard properties of det tell us that,

$$\begin{aligned} \det(X_{ij}) &= \sum_{\text{permutation } \pi} \text{sgn}(\pi) X_{1\pi(1)} \dots X_{n\pi(n)} \\ &= \det(X_{ij}) w(v'_1, \dots, v'_n) \end{aligned}$$

End Lec 23 = $[v'_1, \dots, v'_n] (w'_1, \dots, w'_n) w(v'_1, \dots, v'_n)$

$$w = w(v'_1, \dots, v'_n) [v'_1, \dots, v'_n]$$

~~Corollary 6.6~~ Let $w_1, \dots, w_n, v_1, \dots, v_n$ be bases & $w_i = \sum X_{ij} v_j$
 then $[v_1, \dots, v_n] = \det X_{ij} [w_1, \dots, w_n]$
 If $X = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$

~~then $|\det(X)| = \text{area} \left(\begin{matrix} (b,d) \\ \nearrow \\ (a,c) \end{matrix} \right)$~~

~~More generally if $X = (v'_1, \dots, v'_n)$~~

~~$$|\det(X)| = \text{vol}_n \left\{ \sum \epsilon_i v_i \mid 0 \leq \epsilon_i \leq 1 \right\}$$~~

~~In many problems we want area to~~

~~have a sign $\int_a^b f(x) dx = - \int_b^a f(x) dx$~~

~~This relates to orientation.~~