

Lecture 20

20.1

Recall $\tilde{\gamma} : (a, b) \rightarrow C$
 on arc-length parameterised / curve
 oriented

Have 3 ~~different~~ funct

$$T, N, B : C \rightarrow \mathbb{R}^3$$

defined as follow - If $c = \tilde{\gamma}(t)$

$$T(c) = \tilde{\gamma}'(c)$$

$$N(c) = \frac{T'(c)}{\|T'(c)\|} \quad (T'(c) \neq 0)$$

$$B(c) = T(c) \times N(c)$$

Proof" 4.10 Let $\gamma : (a, b) \rightarrow C$ be a parameterised
 curve oriented curve & $c = \gamma(t)$ then

$$T(c) = \frac{\gamma'(t)}{\|\gamma'(t)\|} \quad N(c) = \frac{T'(c)}{\|T'(c)\|}$$

Here $T'(c)$ means $T'(c) = \frac{d}{dt} T(\gamma(t))$

Pruf Let $\tilde{\gamma}(t)$ be derivative wrt
 arc-length & $\tilde{\gamma}(t) = \gamma(p(t))$ be
 $\tilde{\gamma}(t) = \gamma'(p(t)) \frac{dp}{dt}(t)$

Proof

$$\text{we have } \tilde{\gamma}(t) = \gamma(\rho(t))$$

$$\therefore \dot{\tilde{\gamma}}(t) = \gamma'(\rho(t)) \frac{d\rho}{dt}(t)$$

$$\text{as } \|\dot{\tilde{\gamma}}(t)\| = 1 \text{ get } \|\gamma'(\rho(t))\| = \frac{d\rho}{dt}(t)$$

$$\therefore \dot{\tilde{\gamma}}(t) = \frac{\gamma'(\rho(t))}{\|\gamma'(\rho(t))\|}$$

$$\therefore \cancel{Tf} \quad c = \tilde{\gamma}(t) = \gamma^*(\rho(t)).$$

$$\cancel{T} T(c) = \dot{\tilde{\gamma}}(t) = \frac{\gamma'(\rho(t))}{\|\gamma'(\rho(t))\|} = \gamma'(s).$$

T is unit tangent vector in direction of orientation

$$= \frac{\gamma'(s)}{\|\gamma'(s)\|}$$

Now we think of T as a function of t

$$\text{or by } T(\tilde{\gamma}(t))$$

$$\text{or } \dot{T} = \frac{d}{dt} T(\tilde{\gamma}(t))$$

$$\text{or } \cancel{T} = T(\gamma(s))$$

$$T(s) = \frac{d}{ds} T(\gamma(s)) =$$

$$\therefore \dot{T}(\tilde{\gamma}(t))$$

$$= T'(\gamma(\rho(t))) \frac{d\rho}{dt}(t)$$

$$\cancel{T}$$

$$\frac{T}{\|\dot{T}\|}(\tilde{\gamma}(t))$$

$$= \frac{T'(\gamma(\rho(t)))}{\|T'(\gamma(\rho(t)))\|}$$

This makes the helix calculation easier:

$$\gamma(t) = (a \sin(t), a \cos(t), b t)$$

$$\gamma'(t) = (a \cos(t), -a \sin(t), b)$$

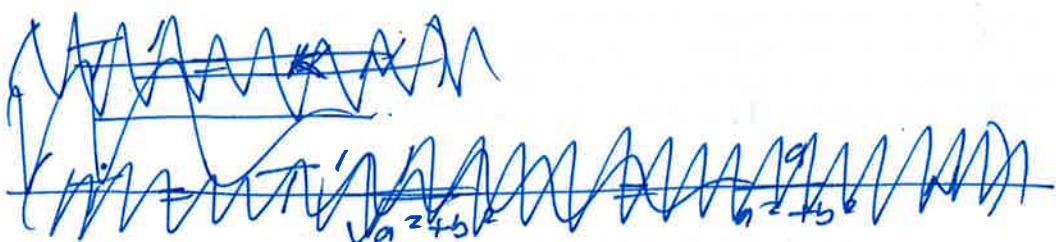
$$\|\gamma'(t)\| = \sqrt{a^2 + b^2}$$

$$T = \frac{\gamma'}{\|\gamma'\|} = \frac{1}{\sqrt{a^2 + b^2}} (a \cos(t), -a \sin(t), b)$$

$$T' = \frac{1}{\sqrt{a^2 + b^2}} (-a \sin(t), -a \cos(t), 0)$$

$$N = \frac{T'}{\|T'\|} = (-\sin(t), -\cos(t), 0)$$

$$B = T \times N = \frac{1}{\sqrt{a^2 + b^2}} (b \sin(t), -b \cos(t), a)$$



all vectors at $c = \underline{(a \sin(t), a \cos(t), b t)}$



~~So if~~ $c = \tilde{\gamma}(t) = \gamma(s)$ ($s = \rho(t)$)

$$N(c) = \frac{\dot{T}}{\|\dot{T}\|} (\tilde{\gamma}(t)) = \frac{T'/\gamma(\cancel{s})}{\|T'/\gamma(\cancel{s})\|} = N(c).$$

§5 Geometry of Surfaces (the outline needs fixing.)

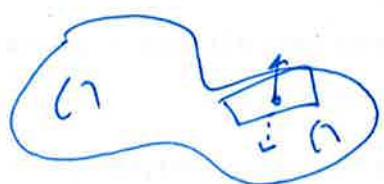
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smooth

We have defined a surface to be a 2-dens^l submanifold. We will assume from now on that it is in \mathbb{R}^3 .

If $\Sigma \subseteq \mathbb{R}^3$ is a surface $T_x \Sigma$ is 2-dens^l. So $(T_x \Sigma)^\perp$ is 1-dens^l.

$\therefore (T_x \Sigma)^\perp$ for x has two connected components. If there are the normal directions at x or the possible non-normal vectors. A continuous choice for all $x \in \Sigma$ of a normal direction is called an orientation of Σ and Σ is an oriented surface.



If $\psi: U \rightarrow \Sigma$ is a parametrisation then $\frac{\partial \psi}{\partial x^1} \times \frac{\partial \psi}{\partial x^2}$ is normal and we say ψ is an oriented parametrisation if this is in the chosen normal direction.

Example

Let $F: \mathbb{R}^3 \rightarrow \mathbb{R}$ & $\Sigma = F^{-1}(0)$.

~~$F'(x) \neq 0$ always~~ $\forall x \in \Sigma$

If $\text{grad } F(x) = (F'_1(x), F'_2(x), F'_3(x))$

then $F'(x)(v) = \langle \text{grad } F(x), v \rangle$

$\text{so } \text{grad } F(x) \perp T_x \Sigma$

& we can use it to define the normal direction.

If $n(x)$ is the unit normal to the oriented surface Σ then n is smooth because locally

$$n(\Psi(x_1, x_2)) = \frac{\frac{\partial \Psi}{\partial x_2}(x_1, x_2) \times \frac{\partial \Psi}{\partial x_1}(x_1, x_2)}{\left\| \frac{\partial \Psi}{\partial x_1}(x_1, x_2) \times \frac{\partial \Psi}{\partial x_2}(x_1, x_2) \right\|}$$

$$\therefore n \cdot \Psi(x_1, x_2) = \text{which is smooth}$$

The unit normal therefore defines a smooth function

$$n: \overset{\text{smooth}}{\cancel{\Sigma}} \rightarrow S^2 \subseteq \mathbb{R}^3$$

called the Gauss map of Σ

The second fundamental form

Let $\Sigma \subseteq \mathbb{R}^3$ an oriented surface, $s \in \Sigma$ and n the oriented unit normal at s .

Let $\phi: U \subseteq \mathbb{R}^2 \xrightarrow{\text{open}} \Sigma$ be a parametrisation with $\phi(0,0) = s$.

$$\text{Let } v, w \in T_s \Sigma \text{ so } v = \sum_{i=1}^2 v^i \frac{\partial \phi}{\partial x^i}(0,0)$$

$$w = \sum_{i=1}^2 w^i \frac{\partial \phi}{\partial x^i}(0,0)$$

we define the second fundamental form

$$\alpha: T_s \Sigma \times T_s \Sigma \rightarrow \mathbb{R}$$

$$\text{by } \alpha(v, w) = \sum_{i,j} \left\langle \frac{\partial^2 \phi}{\partial x^i \partial x^j}(0,0), n \right\rangle v^i w^j$$

$$\therefore \nabla n'(s) \in T_s \Sigma$$

Consider

$$\therefore \langle n'(s)(v), w \rangle$$



Think of n as $n \circ \varphi$ with respect to parameters. Then

$$\frac{\partial}{\partial x^i} n \circ \varphi = \frac{\partial n}{\partial x^i} \circ \varphi^{-1} \cdot \frac{\partial \varphi}{\partial x^i}$$

Want ~~$\frac{\partial}{\partial x^i} n \circ \varphi$~~ to calculate

$$n'(s)(v)$$

Choose α so that $\varphi'(0,0)(\alpha) = v$

$$\text{then } n'(s)(v) = n'(s) \varphi'(0,0)(\alpha) = \sum \frac{\partial n \circ \varphi}{\partial x^i}(0,0) \alpha^i$$

$$\text{But } \varphi'(0,0)(e^i) = \frac{\partial \varphi}{\partial x^i}(0,0).$$

$$\therefore \varphi'(0,0)(\alpha) = \sum_i \frac{\partial \varphi}{\partial x^i}(0,0) \alpha^i$$

$$\therefore n'(s)(v) = \frac{\partial n \circ \varphi}{\partial x^i}(0,0) \alpha^i$$

But $v = \sum v_i \frac{\partial \psi}{\partial x^i}$

$$= \sum v_i \frac{\partial x^e}{\partial x^i} \frac{\partial p^e}{\partial x^i}$$

$$= \sum \left(\sum v_i \frac{\partial p^e}{\partial x^i} \right) \frac{\partial x^e}{\partial x^i}$$

~~more~~

This is coefficient of $\alpha \in \frac{\partial x^e}{\partial x^i}$

hence

$\therefore \alpha$ defined using x basis

~~$\langle \frac{\partial^2 x^i}{\partial x^k \partial x^j}, n \rangle \left(\sum v_i \frac{\partial p^e}{\partial x^i} \right) \left(\sum w^k \frac{\partial p^k}{\partial x^j} \right)$~~

⑫ Variation

Recall
that $n: S \rightarrow \mathbb{R}^3$ is smooth

as locally it looks like

$$\begin{pmatrix} \frac{\partial \psi}{\partial x^1} & \frac{\partial \psi}{\partial x^2} \\ \frac{\partial x^1}{\partial x^1} & \frac{\partial x^2}{\partial x^2} \\ \frac{\partial x^1}{\partial x^1} \times \frac{\partial x^2}{\partial x^2} \end{pmatrix}$$

So we can differentiate at

$$n'(s): T_s S \rightarrow \mathbb{R}^3$$

as $\langle n, n \rangle = 1$ we have $\langle n'(s), n(s) \rangle = 0$

$$\therefore \langle n'(v), w \rangle = \sum_{i,j} \left\langle \frac{\partial n \circ \Psi}{\partial x^i} v^i, \frac{\partial \Psi}{\partial x^j} w^j \right\rangle$$

$$= \sum_{i,j} \left\langle \frac{\partial n \circ \Psi}{\partial x^i}, \frac{\partial \Psi}{\partial x^j} \right\rangle v^i w^j$$

$$\text{But } \left\langle n \circ \Psi, \frac{\partial \Psi}{\partial x^i} \right\rangle = 0$$

$$\therefore \left\langle \frac{\partial n \circ \Psi}{\partial x^i}, \frac{\partial \Psi}{\partial x^j} \right\rangle + \left\langle n, \frac{\partial^2 \Psi}{\partial x^i \partial x^j} \right\rangle = 0$$

$$\therefore \langle n'(v), w \rangle = - \sum_{i,j} \left\langle \frac{\partial n \circ \Psi}{\partial x^i}, \frac{\partial^2 \Psi}{\partial x^j \partial x^i} \right\rangle v^i w^j$$

$$= - \alpha(v, w)$$

So LHS doesn't depend on parameter!

Propⁿ 5.1. Let $\alpha: T_S \Sigma \times T_S \Sigma \rightarrow \mathbb{R}$

be the second fundamental form on Σ .

Then

① α is bilinear & symmetric

$$\text{i.e. } \alpha(v, w) = \alpha(w, v)$$

$$\alpha(\lambda v + \mu u, w) = \lambda \alpha(v, w) + \mu \alpha(u, w)$$

~~$$\alpha(v, \lambda u + \mu w) = \lambda \alpha(v, u) + \mu \alpha(v, w)$$~~