

§0 Introduction

* Handouts

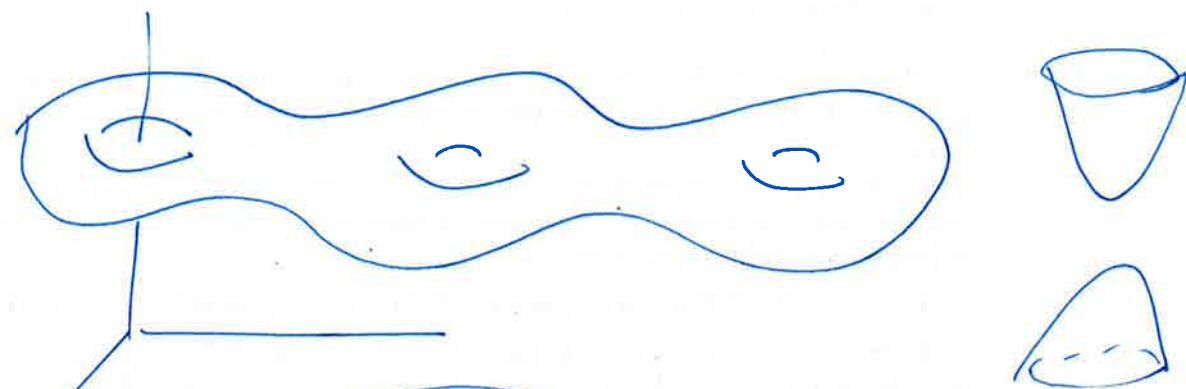
* Consulting time next lectures

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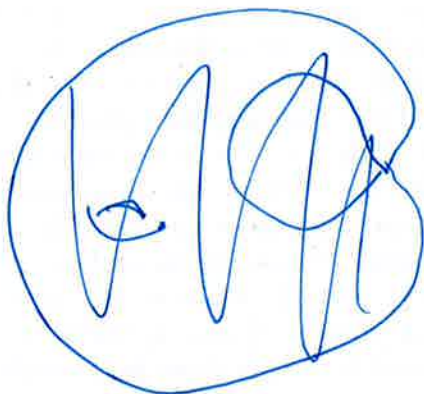
A surface is a special kind of (smooth) subset of \mathbb{R}^3 .

EG: $S^2 = \{ (x, y, z) \mid x^2 + y^2 + z^2 = 1 \}$

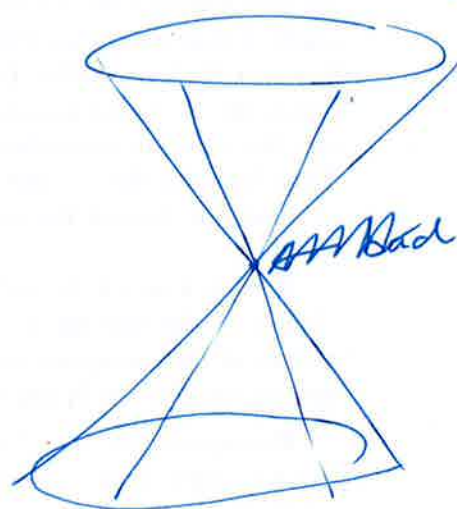
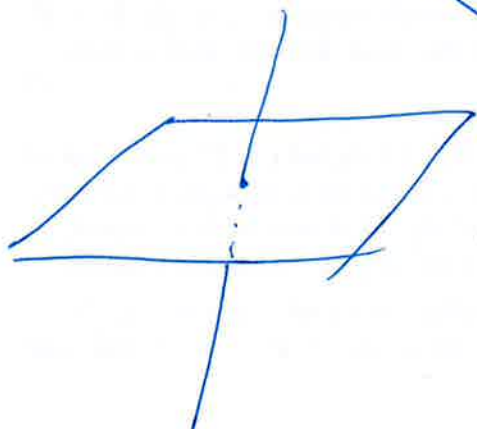
or



not smooth:



"2-dimensional"

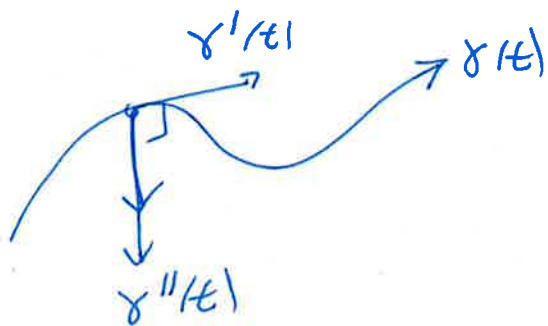


A surface is an example of a manifold and in particular of a submanifold of \mathbb{R}^3 . (\mathbb{R}^3 is also a manifold.)

We want to prove the Gauss-Bonnet Theorem

It is possible to state this without defining too much so let me do that.

① Start with curves in \mathbb{R}^2



$\gamma: (a,b) \rightarrow \mathbb{R}^2$
differentiable

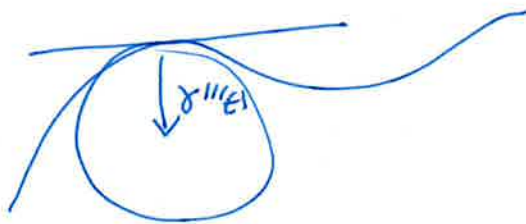
Assume $\langle \gamma'(t), \gamma''(t) \rangle = 1 \quad \therefore \langle \gamma''(t), \gamma'(t) \rangle = 0$

$\gamma'(t)$ velocity

$\gamma''(t)$ acceleration

Define curvature as $\|\gamma''(t)\|$.

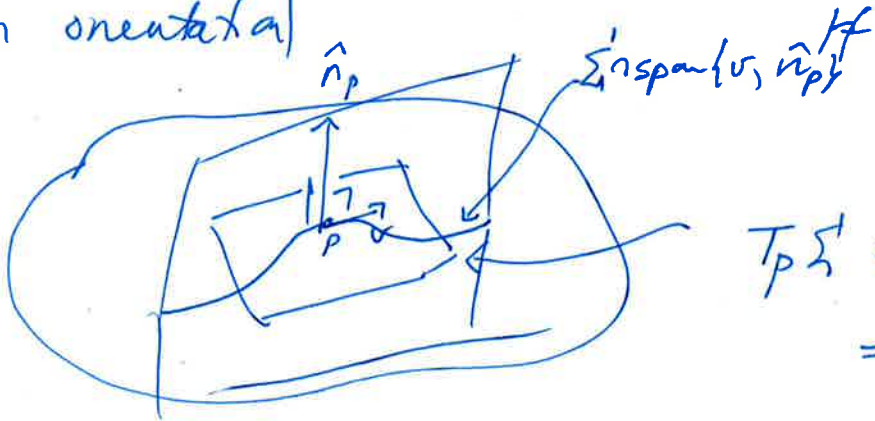
Also radius of circle of "best fit"



② Now consider Σ^+ a surface

$p \in \Sigma^+$ $\hat{n}_p =$ unit normal

need to choose a direction for \hat{n}_p (called an orientation)




$$T_p \Sigma = \{v \in \mathbb{R}^3 \mid \langle v, \hat{n}_p \rangle = 0\} = (\hat{n}_p)^\perp$$

tangent space to Σ at p

imagine you are \hat{n}_p

If $v \in T_p \Sigma$ $\{v, \hat{n}_p\}$ span a 2-dim space and $\cap \Sigma$ on a curve γ_v say.

Define $\kappa(v, v) =$ curvature of $\gamma_v \leftarrow$ (can make κ have a sign)

Remarkable fact ~~$\kappa(v, v)$~~ There is an  quadratic & symmetric form κ s.t. $\kappa(v, v) =$ result above

Let $\lambda_1 =$ largest curvature $\lambda_2 =$ smallest curvature — principal curvatures

$K = \lambda_1 \lambda_2 =$ Gaussian curvature

$H = \frac{1}{2}(\lambda_1 + \lambda_2) =$ mean curvature

Gauss - Bonnet : $\frac{1}{2\pi} \iint K dS = 2 - 2g$
of holes \uparrow

4

6.4

 $g=0$

 $g=1$

 $g=2$

NB

LHS - differential change if we ~~quickly~~ deform surface

RTS - topological

doesn't change if we deform surface.

Example of an index th^m - fundamental

Classification th^m for compact, orientable surface

p to $homo^m$



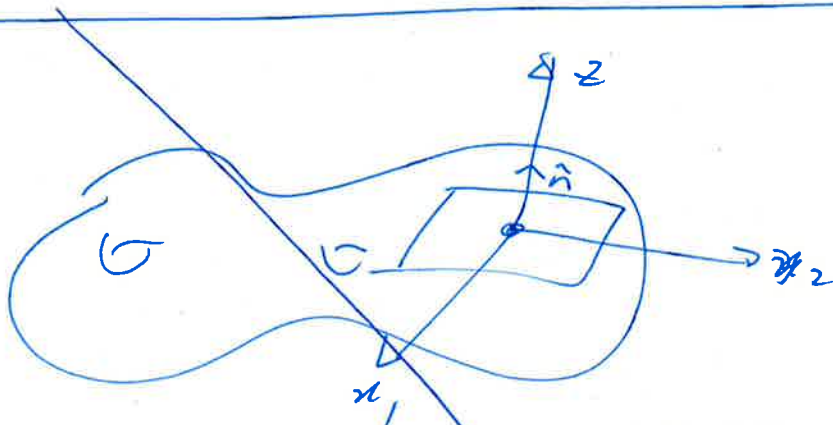
Determined by genus - $2g-2 = \text{Euler class}$

TRIANGULATION χ -class
 $\# \text{ faces} - \# \text{ edges} + \# \text{ vertices}$

Mean curvature $H=0$ - minimal surface.

locally has smallest area. "soap bubbles".

What is π ?



locally $\Sigma : z = f(x_1, x_2) \neq$

$f(0,0) = 0$

$f_x(0,0) = 0$

$f_y(0,0) = 0$

$z = \frac{\partial f}{\partial x_1} x_1 + \frac{\partial f}{\partial x_2} x_2 + \frac{1}{2} \frac{\partial^2 f}{\partial x_1^2} x_1^2 + \frac{1}{2} \frac{\partial^2 f}{\partial x_2^2} x_2^2 + \frac{\partial^2 f}{\partial x_1 \partial x_2} x_1 x_2 + \dots$

② 0.5

$$\Pi = \left(\frac{\partial^2 f}{\partial x^i \partial x^j} (0,0) \right) \text{ "Hessian"}$$

we need to go back and develop the definition of submanifolds & tools for solving these problems.

Note formally if we exchange the definition of ϵ

other kinds of geometry

One way to define a submanifold is to say it is defined by an eqⁿ

$$f(x, y, z) = 0 \quad \text{where } f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

is differentiable & $f'(x, y, z) \neq 0$. if $f(x, y, z) = 0$

E.g. $f(x, y, z) = x^2 + y^2 + z^2 - 1$

Other geometries arise by taking

different kinds of functions.

Eg $f(x, y, z)$ a polynomial.

Then the properties of $\mathbb{R}[x, y, z]$ are

important. (More generally $\mathbb{F}[x_1, \dots, x_n]$)

a ~~field~~ \mathbb{F} a field \rightarrow algebraic geometry

(Fields & Geometry) \mathbb{F}^n

1. Review

Notation \mathbb{R} real numbers
 $\mathbb{N} = \{1, 2, 3, \dots\}$ natural numbers
 $\mathbb{R}^n = n$ -tuples $x = (x^1, \dots, x^n)$ (vectors)

no bold face, underline, arrows etc for vectors

If $x = (x^1, \dots, x^n)$ $y = (y^1, \dots, y^n)$

$\langle x, y \rangle = x^1 y^1 + \dots + x^n y^n$ inner product

$\|x\| = \sqrt{\langle x, x \rangle} = \sqrt{(x^1)^2 + \dots + (x^n)^2}$ norm or length of x .

NB $\|x\| = 0 \iff x = 0$

These satisfy:

$\langle x, y \rangle \leq \|x\| \|y\|$ Cauchy's

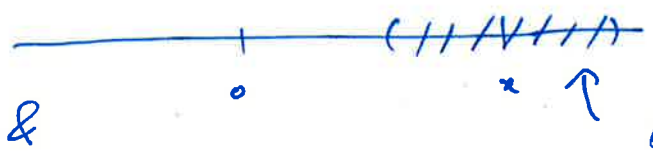
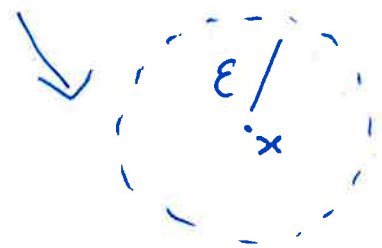
Exercise $\int_0^1 \int_0^1 \langle x - \frac{\langle x, y \rangle y}{\langle y, y \rangle}, x - \frac{\langle x, y \rangle y}{\langle y, y \rangle} \rangle > 0$ inequality

(Square & use Cauchy) $\|x + y\| \leq \|x\| + \|y\|$ Δ inequality

If $x \in \mathbb{R}^n$, $\epsilon > 0$ $\max\{|x^1|, \dots, |x^n|\} \leq \|x\| \leq \sqrt{n} \max\{|x^1|, \dots, |x^n|\}$ Exercise

$B(x, \epsilon) = \{y \in \mathbb{R}^n \mid \|x - y\| < \epsilon\}$

$\frac{1}{n}$
 $n=1$ $\|x\| = |x|$



$B(x, \epsilon) = (x - \epsilon, x + \epsilon)$

A subset $U \subseteq \mathbb{R}^n$ is called open if $\forall x \in U \exists \epsilon > 0$ s.t. $B(x, \epsilon) \subseteq U$.



NB ϵ depends on x usually.

A sequence in \mathbb{R}^n is a function $\mathbb{N} = \{1, 2, \dots\} \rightarrow \mathbb{R}^n$

usually we write ~~$\mathbb{N} \rightarrow \mathbb{R}^n$~~ $\{x_n\}_{n \in \mathbb{N}}$ or just

~~x_1, x_2, \dots~~ or just x_n .

DECIMAL PLACES

A sequence $\{x_n\}$ has limit x if $\forall \epsilon > 0 \exists N$ s.t. $\forall n > N \quad \|x_n - x\| \leq \epsilon$

or if $\lim_{n \rightarrow \infty} \|x_n - x\| = 0$.

SEQUENCE OF REAL NUMBERS

In such a case x is unique & we

write $\lim_{n \rightarrow \infty} x_n = x$ or $x_n \rightarrow x$

End Lecture 1 2011

Lemma If $x_n \rightarrow x$ then $\lim_{m, n \rightarrow \infty} \|x_m - x_n\| = 0$

Proof

~~$$0 \leq \|x_m - x_n\| = \|(x_m - x) - (x_n - x)\| \leq \|x_m - x\| + \|x_n - x\|$$~~