

Predicting turbulence

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12 August 2009

Turbulence

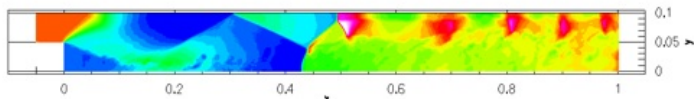
- Turbulence is a state of flow characterised by unsteady, three-dimensional fluid motion over a wide range of spatial and temporal scales.

Turbulence

- Turbulence enhances mixing and increases energy dissipation.

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Dimotakis *et al.*, Caltech

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NASA

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- The Reynolds number is

$$Re = \frac{UL}{\nu}.$$

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- See <http://www.claymath.org/millennium/>

Direct numerical simulation (DNS)

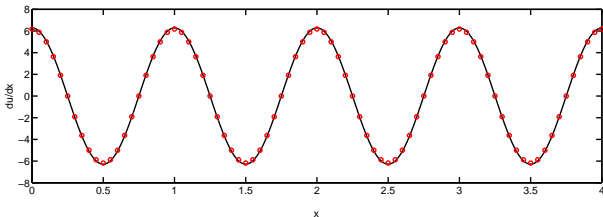
- Use numerical methods to obtain an approximate solution.
 - finite difference
 - finite element
 - finite volume
 - spectral
 - meshless
- Must resolve large and small (fine) scales simultaneously.

Resolution of finite difference schemes

- Let $x_i = i \Delta x$ and $u_i = u(x_i)$, where i is an integer.

$$\left. \frac{du}{dx} \right|_i = \frac{u_{i+1} - u_{i-1}}{2\Delta x} + O(\Delta x^2)$$

- Suppose $u(x) = \sin(2\pi x)$.

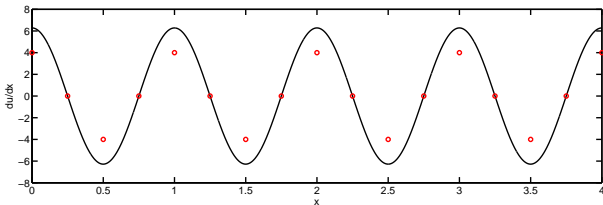


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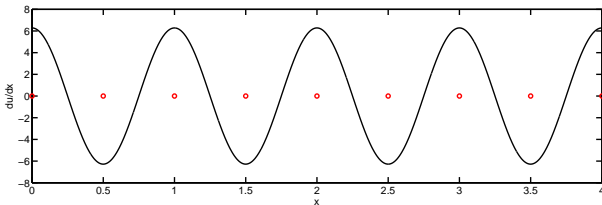


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Scale separation in turbulence

- Let ϵ be the energy dissipation rate per unit mass. It is observed that the finest length scale η depends on ϵ and the viscosity ν . Dimensional analysis implies

$$\eta \sim \left(\frac{\nu^3}{\epsilon} \right)^{1/4}$$

- It is observed that the dissipation is determined by U and L , which characterise the large-scale flow. Dimensional analysis implies

$$\epsilon \sim \frac{U^3}{L}$$

- Thus

$$\frac{\eta}{L} \sim Re^{-3/4}$$

Computational work for DNS

- The number of grid points needed is

$$N \sim \left(\frac{L}{\Delta x} \right)^3 = Re^{9/4}$$

- The number of time steps needed is

$$M \sim \frac{T}{\Delta t} \sim \frac{UT}{\Delta x} \sim Re^{3/4}$$

- The computational work is proportional to

$$MN \sim Re^3$$

Computational time for DNS

- For air, $\nu \approx 8 \times 10^{-6} \text{ m}^2/\text{s}$.

	U	L	Re	Wall-clock time
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- The Universe is about 14 billion years old.
- DNS is not feasible for such flows.

Large-eddy simulation (LES)

- Smooth flow variables using a filter

$$\bar{\phi}(\mathbf{x}) = \int \phi(\mathbf{x}') G(\mathbf{x} - \mathbf{x}'; \Delta) d\mathbf{x}'$$

- Apply to Navier–Stokes equations

$$\frac{\partial \bar{u}_j}{\partial x_j} = 0$$
$$\frac{\partial \bar{u}_i}{\partial t} + \frac{\partial \bar{u}_i \bar{u}_j}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \frac{1}{Re} \frac{\partial^2 \bar{u}_i}{\partial x_j^2} - \frac{\partial T_{ij}}{\partial x_j}$$

- The subgrid-scale (SGS) stress is

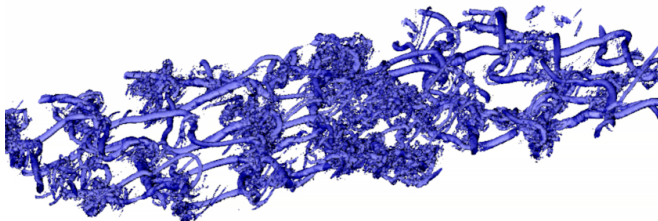
$$T_{ij} = \overline{u_i u_j} - \bar{u}_i \bar{u}_j$$

Subgrid-scale motion

- The vorticity is

$$\boldsymbol{\omega} = \nabla \times \boldsymbol{u}$$

It is related to the rotation of fluid elements.



An exact solution

- Vorticity is transported by the fluid. It is intensified by stretching and diffused by viscosity.
- An exact solution of the Navier–Stokes equation in cylindrical coordinates (r, θ, z) is

$$u_r = -\frac{1}{2}ar, \quad u_z = az, \quad u_\theta = \frac{\Gamma}{2\pi r} \left(1 - e^{-ar^2/4\nu}\right)$$

This is an axisymmetric solution.

- The vorticity is aligned in the z direction

$$\omega_z = \frac{a}{2\nu} e^{-ar^2/4\nu}$$

An asymptotic solution

- Introduce stretched coordinates

$$\rho = e^{at/2} r \quad \text{and} \quad \tau = \frac{e^{at} - 1}{a}$$

- The vorticity is

$$\omega_z = \sum_{n=-\infty}^{\infty} \omega_n(\rho, \tau) e^{in\theta},$$

$$\omega_n(\rho, \tau) = f_n(\rho) e^{-in\Omega(\rho)\tau - \nu^2 \Omega'^2(\rho) \tau^3/3}$$

- The error is $O(\tau^{-1})$

Stretched-vortex subgrid-scale stress model

- Model turbulence as a homogeneous ensemble of nonaxisymmetric stretched vortices.
- Start with the vorticity correlation function

$$\begin{aligned} W_{ij}(\boldsymbol{\rho}) &= \overline{\omega_i(\mathbf{x})\omega_j(\mathbf{x} + \boldsymbol{\rho})} \\ &= \int_0^\pi \int_0^{2\pi} \int_0^{2\pi} F_{ij} P(\alpha, \beta, \gamma) \sin \alpha \, d\alpha \, d\beta \, d\gamma \end{aligned}$$

$$\begin{aligned} F_{ij} &= \frac{\sum_m l_m}{L^3} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \omega_z^{(m)}(x'_1, x'_2, t) \omega_z^{(m)}(x'_1 + \rho'_1, x'_2 + \rho'_2, t) \\ &\quad \times E_{3i} E_{3j} \, dx'_1 \, dx'_2 \end{aligned}$$

Stretched-vortex subgrid-scale stress model

- Assume that vortices are aligned with the unit-vector e^v . Then it is found that

$$T_{ij} = \overline{u_i u_j} = K(\delta_{ij} - e_i^v e_j^v)$$

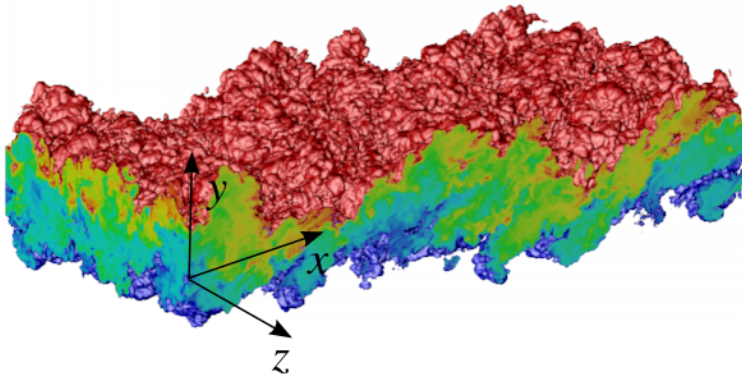
$$K = \int_{k_c}^{\infty} E(k) dk$$

- For nonaxisymmetric stretched-spiral vortices, it is found that

$$E(k) = \mathcal{K}_0 \epsilon^{2/3} k^{-5/3} e^{-2k^2 \nu / 3a}$$

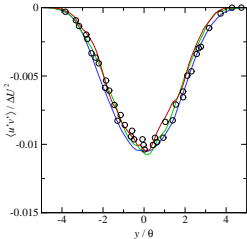
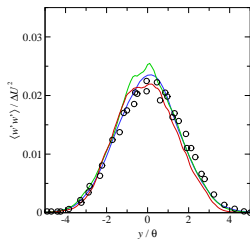
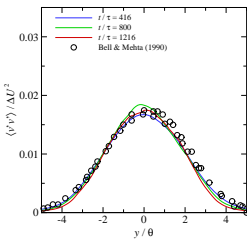
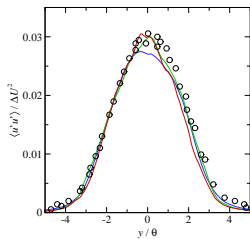
- The parameters $\mathcal{K}_0 \epsilon^{2/3}$, a and e^v are estimated from the resolved-scale flow.

Turbulent mixing layers

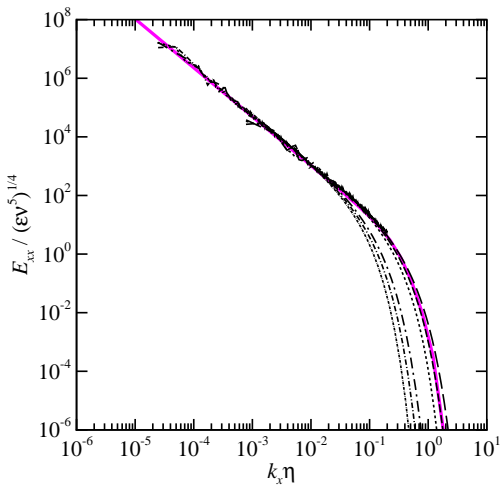


Turbulent mixing layers

Reynolds-stress tensor – *cf.* Bell & Mehta (1990)



Velocity spectra



Conclusion

- Turbulence is governed by the Navier–Stokes equations
- It is presently impossible to obtain solutions to high Reynolds number turbulent flows.
- Nevertheless, large-eddy simulations using subgrid-scale models produce statistics that are consistent with experimental data.
- Further work:
 - Variable density flows
 - Reacting flows
 - Multiphase flows
 - Transition

Conclusion

I am an old man now, and when I die and go to heaven there are two matters on which I hope for enlightenment. One is quantum electrodynamics, and the other is the turbulent motion of fluids. And about the former I am rather optimistic.

Horace Lamb, 1932