

## Variational Methods and Optimal Control

### Class Exercise 1 solutions

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1. 0 marks Use the technique of Lagrange multipliers to maximize  $V = xyz$  for  $x, y, z \geq 0$  subject to the pair of constraints

$$\begin{aligned} xy + yz + zx &= 1 \\ x + y + z &= 3 \end{aligned}$$

**Solution:** Introduce slack variables  $\alpha, \beta, \gamma$  to express the inequalities  $x, y, z \geq 0$  as  $x - \alpha^2 = 0, y - \beta^2 = 0, z - \gamma^2 = 0$ . We employ Lagrange multipliers to form the new objective function

$$\mathcal{L} = xyz + \lambda_1(xy + yz + zx - 1) + \lambda_2(x + y + z - 3) + \lambda_3(x - \alpha^2) + \lambda_4(y - \beta^2) + \lambda_5(z - \gamma^2).$$

First we deal with the last three terms. The equation  $\partial\mathcal{L}/\partial\alpha = 0$  yields  $\lambda_3(-2\alpha) = 0$ , so either  $\lambda_3 = 0$  or  $\alpha = 0$ . Similarly either  $\lambda_4 = 0$  or  $\beta = 0$ , and either  $\lambda_5 = 0$  or  $\gamma = 0$ . If any of  $\lambda_3, \lambda_4, \lambda_5$  is nonzero, then at least one of  $\alpha, \beta, \gamma$  is zero and therefore at least one of  $x, y, z$  is zero. Hence  $V = 0$ . Since  $x, y, z \geq 0$ , this corresponds to a global minimum. So we must take  $\lambda_3 = \lambda_4 = \lambda_5 = 0$  for a maximum.

Note that if  $x = y = z = v$ , say, then the second constraint implies  $v = 1$  and the first constraint  $v^2 = 1/3$ , a contradiction. Hence we can't have  $x = y = z$ .

The equation  $\partial\mathcal{L}/\partial x = 0$  provides

$$yz + \lambda_1(y + z) + \lambda_2 = 0.$$

By symmetry we have also

$$zx + \lambda_1(z + x) + \lambda_2 = 0.$$

Subtraction yields

$$z(y - x) + \lambda_1(y - x) = 0 \quad \text{or} \quad (z + \lambda_1)(y - x) = 0.$$

Hence either

$$x = y \quad \text{or} \quad z = -\lambda_1.$$

By symmetry

$$y = z \quad \text{or} \quad x = -\lambda_1$$

and

$$z = x \quad \text{or} \quad y = -\lambda_1.$$

We can't have any two of  $x = y, y = z, z = x$ , for then  $x = y = z$ . Similarly we can't have all of  $z = -\lambda_1, x = -\lambda_1, y = -\lambda_1$ . Hence we must have

$$x = y, x = -\lambda_1, y = -\lambda_1, \quad \text{that is} \quad x = y = -\lambda_1,$$

or

$$y = z = -\lambda_1,$$

or

$$z = x = -\lambda_1.$$

With the first possibility, the second constraint gives  $z = 3 - 2x$  and the first constraint  $x^2 + 2xz = 1$ , so

$$x^2 + 2x(3 - 2x) = 1 \quad \text{or} \quad 3x^2 - 6x + 1 = 0.$$

Hence

$$x = 1 \pm \frac{\sqrt{6}}{3} \quad \text{and therefore} \quad y = 1 \pm \frac{\sqrt{6}}{3} \quad \text{and} \quad z = 1 \mp \frac{2\sqrt{6}}{3}.$$

Now  $1 - 2\sqrt{6}/3 < 0$ , so to get  $V > 0$  we must choose

$$x = y = 1 - \frac{\sqrt{6}}{3}, \quad z = 1 + \frac{2\sqrt{6}}{3}$$

which leads to

$$V = xyz = -1 + \frac{4\sqrt{6}}{9}.$$

The same value arises from the cyclic permutations

$$y = z = 1 - \frac{\sqrt{6}}{3}, \quad x = 1 + \frac{2\sqrt{6}}{3}$$

and

$$z = x = 1 - \frac{\sqrt{6}}{3}, \quad y = 1 + \frac{2\sqrt{6}}{3}.$$

2. 0 marks Maximize  $V = x^2 + 2y^2 - z^2$  subject to

$$x^2 + y^2 + z^2 \leq 1$$

**Solution:** Use a slack variable  $u$  to express the constraint as an equality

$$x^2 + y^2 + z^2 + u^2 = 1.$$

This leads to a new objective function

$$\mathcal{L} = V + \lambda(x^2 + y^2 + z^2 + u^2 - 1).$$

The condition  $\partial\mathcal{L}/\partial x = 0$  gives

$$2x + \lambda \cdot 2x = 0, \quad \text{so} \quad 2x(1 + \lambda) = 0 \quad \text{and} \quad x = 0 \quad \text{or} \quad \lambda = -1.$$

Partial differential with respect to  $y, z, u$  in turn give similarly

$$y = 0 \quad \text{or} \quad \lambda = -2;$$

$$z = 0 \quad \text{or} \quad \lambda = 1;$$

$$u = 0 \quad \text{or} \quad \lambda = 0.$$

By the constraint, we can't have all of  $x, y, z, u$  equal to zero. Hence we must have either

$$\lambda = -1, y = z = u = 0, \quad \text{or}$$

$$\lambda = -2, x = z = u = 0, \quad \text{or}$$

$$\lambda = 1, x = y = u = 0, \quad \text{or}$$

$$\lambda = 0, x = y = z = 0.$$

In the first case, the constraint gives  $x^2 = 1$  and  $V = 1$ . Similarly the other three cases in turn yield  $y^2 = 1$  and  $V = 2; z^2 = 1$  and  $V = -1; u^2 = 1$  and  $V = 0$ . Thus the maximum is  $V = 2$ , and this arises when  $x = z = 0$  and  $y = \pm 1$ .

3. [5 marks] Which of the following are functionals of the function  $y(x)$  (label yes or no).

**Solution:**

- (a)  $y(0) + 4$                       yes  
 (b)  $\frac{dy}{dx}\bigg|_0$                       yes (assuming the derivative exists)  
 (c)  $\min\{y(x) | 0 \leq x \leq 1\}$     yes (assuming the minimum exists)  
 (d)  $\int_0^1 y \, dx$                       yes  
 (e)  $\int_0^\pi \left[\frac{d^n y}{dx^n}\right]^3 f(x) \, dx$     yes (assuming the derivatives exist)

4. [1 mark] Given the  $L^2$ -norm  $\|f\|_2 = \sqrt{\int_0^1 f(x)^2 \, dx}$  on the vector space  $L^2[0, 1]$ , describe (in one sentence) the  $\varepsilon$ -neighbourhood of the function  $y = x$ .

**Solution:**

The  $\varepsilon$ -neighbourhood of the function  $y = x$  is the set of functions within distance  $\varepsilon$  of  $y = x$ , where distance is defined using the  $L^2$  norm of the difference between two functions.

5. [4 marks] Find an upper bound for the minimum of the functional

$$J\{y\} = \int_0^1 y^2 y'^2 \, dx,$$

subject to  $y(0) = 0$  and  $y(1) = 1$  using the trial functions

$$y_\varepsilon(x) = x^\varepsilon,$$

with  $\varepsilon > 1/4$ . Justify your argument.

**Solution:**

$$\begin{aligned} y_\varepsilon &= x^\varepsilon \\ y'_\varepsilon &= \varepsilon x^{\varepsilon-1} \end{aligned}$$

and so

$$\begin{aligned} J\{y_\varepsilon\} &= \int_0^1 y^2 y'^2 \, dx \\ &= \varepsilon^2 \int_0^1 x^{4\varepsilon-2} \, dx \\ &= \varepsilon^2 \left[ \frac{x^{4\varepsilon-1}}{4\varepsilon-1} \right]_0^1 \\ &= \frac{\varepsilon^2}{4\varepsilon-1} \\ \frac{dJ\{y_\varepsilon\}}{d\varepsilon} &= \frac{2\varepsilon(4\varepsilon-1) - 4\varepsilon^2}{(4\varepsilon-1)^2} \end{aligned}$$

At a stationary point the derivative is zero and so we require the denominator of  $dJ/d\varepsilon$  to be zero, i.e.,

$$2\varepsilon^2 - \varepsilon = 2\varepsilon(2\varepsilon - 1) = 0,$$

so  $\varepsilon = 0$  or  $1/2$ , but only the latter solution is greater than  $1/4$ , and so this is a stationary point.

We can see it is a minimum by taking the second derivative with respect to  $\varepsilon$  to get

$$\begin{aligned} \frac{d^2 J\{y_\varepsilon\}}{d\varepsilon^2} &= \frac{d}{d\varepsilon} \frac{4\varepsilon^2 - 2\varepsilon}{(4\varepsilon - 1)^2} \\ &= \frac{2}{(4\varepsilon - 1)^3} \end{aligned}$$

which is positive for  $\varepsilon > 1/4$ .

Calculating  $J\{y_\varepsilon\} = \frac{\varepsilon^2}{4\varepsilon-1}$  at the minimum we get  $J\{y^*\} = 1/4$ , which is an upper bound on the true minimum of the functional, because the functional applies over a wider class of possible functions  $y$ , and we know that there may be a better one.